Clustering and classification risks in non-parametric Hidden Markov and I.I.D models

Ibrahim Kaddouri

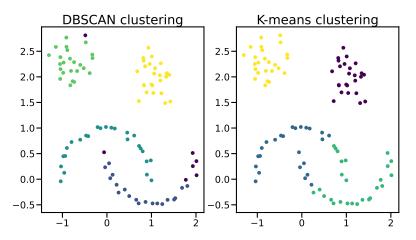
Joint work with Elisabeth Gassiat and Zacharie Naulet

AHIDI2024 Workshop



Clustering

Clustering is an ill-posed problem which aims to find out interesting structures in the data or to derive a useful grouping of the observations.



Model-based clustering: Mixture models

Observations $Y = (Y_k)_{1 \le k \le n}$ coming from J populations. Define latent variables $X = (X_k)_{1 \le k \le n}$ such that: for each k,

$$Y_k \mid X_k = j \sim f_j$$

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Then Y_k has distribution

$$\sum_{j=1}^J \pi_j f_j$$

 π_j : Probability to come from population j

Useful to model data coming from heterogeneous populations.

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Mixture models: Identifiability

Mixture models are not identifiable :

$$\sum_{j=1}^{J} \pi_j f_j = \frac{\pi_1}{2} f_1 + \left(\frac{\pi_1}{2} + \pi_2\right) \left(\frac{\frac{\pi_1}{2} f_1 + \pi_2 f_2}{\frac{\pi_1}{2} + \pi_2}\right) + \sum_{j=3}^{J} \pi_j f_j$$

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Learning of population components possible only under additional structural assumptions such as:

- Parametric mixtures
- Shape restrictions (gaussian, multinomial, ...)

 \rightarrow Might lead to poor results in practice

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Hidden Markov Models and why they are useful

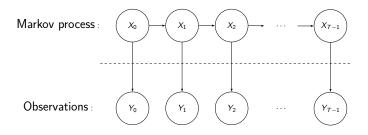


Figure: A Hidden Markov Model.

Latent (unobserved) variables $(X_k)_k$ form a Markov chain. Observations $(Y_k)_k$ are independent conditionnally to $(X_k)_k$.

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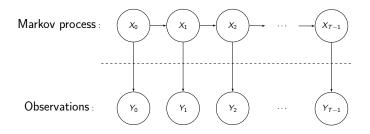


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HMMs are identifiable without any shape restriction!

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Outline



2 Clustering vs Classification





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Risk of classification

Consider the classification loss function:

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Risk of classification

Consider the classification loss function:

$$L_1(x'_{1:n}, x_{1:n}) = \frac{1}{n} \sum_{k=1}^n \mathbf{1}_{x'_k \neq x_k}$$

Let $\theta = (\nu, Q, (f_x)_{1 \le x \le J})$ denote the model parameters. The risk associated to a classifier $h = (h_i)_{1 \le i \le n}$ is:

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The Bayes risk of classification corresponds to $\inf_h \mathcal{R}_n^{class}(\theta, h)$ and the Bayes classifier has a closed formula:

$$h_{\theta}^{\star} = \left(\mathbb{P}_{\theta}\left(X_{i} = . \mid Y_{1:n}\right)\right)_{1 \leq i \leq n}$$

To measure the loss between two partitions A and B of $\{1, .., n\}$, we use the loss

$$L_2(A,B) = 1 - \frac{1}{n} \sup_{\substack{M \subseteq \mathcal{E}(A,B) \\ M \text{ is a matching} \\ \text{between A and B}}} \sum_{\substack{\{C,C'\} \in M}} \operatorname{Card}(C \cap C')$$

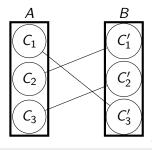
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where the supremum is over the set of matchings which are subsets of the edge set $\mathcal{E}(A, B) := \{ \{C, C'\} : C \in A, C' \in B \}.$



We first define the map π_n by:

$$\pi_n(\mathsf{x}_{1:n}) = \{\{i \ : \ \mathsf{x}_i = \mathsf{a}\} \ : \ \mathsf{a} \in \{1,..,J\}\} \setminus \{\varnothing\}$$



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The risk of a clusterer g can be defined as:

$$\mathcal{R}_n^{clust}(\theta,g) \coloneqq \mathbb{E}_{\theta} \left[L_2(g(Y_{1:n}), \pi_n(X_{1:n})) \right]$$

where

- $\pi_n(X_{1:n})$ is the partition induced by the labels $X_{1:n}$
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The Bayes risk of clustering corresponds to $\inf_{g} \mathcal{R}_{n}^{clust}(\theta, g)$.

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- Is there any relationship between the Bayes classifier and the Bayes clusterer? If so, under what condition?

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The Bayes risk of clustering corresponds to $\inf_{g} \mathcal{R}_{n}^{clust}(\theta, g)$. **Questions:**

- Is there any relationship between the Bayes classifier and the Bayes clusterer? If so, under what condition?
- Under what condition do the Bayes risk of classification and the Bayes risk of clustering have the same magnitude? In what sense?

Relationship between the minimizers

Let J the number of hidden states. Let Θ^{ind} the set of parameters for which observations are independent (all the lines of the transition matrix Q are equal,...) and let Θ^{dep} be the set of the remaining parameters. We recall that g^{\star}_{θ} is the Bayes clusterer and h^{\star}_{θ} the Bayes classifier.

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Theorem

If
$$J = 2$$
, then for all $\theta \in \Theta^{ind}$ and all $n \ge 2$.

$$g_{\theta}^{\star}(Y_{1:n}) = \pi_n \circ h_{\theta}^{\star}(Y_{1:n}) \quad \mathbb{P}_{\theta} \text{-}a.s.$$

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Theorem

If J > 2 or $\theta \in \Theta^{dep}$, then for all $n \ge 2$.

$$\mathbb{P}_{\theta}\left(g_{\theta}^{\star}(Y_{1:n})\neq\pi_{n}\circ h_{\theta}^{\star}(Y_{1:n})\right)>0.$$

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Relationship between the Bayes risks

Theorem

Assume $\delta = \min_{i,j} Q_{i,j} > 0$. For J = 2 and $\theta \in \Theta^{ind} \cup \Theta^{dep}$, there exist $c, c', \beta > 0$ depending only on δ such that

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For J>2 and $\theta\in\Theta^{\mathrm{ind}}\cup\Theta^{\mathrm{dep}}$ and all $n\geq 1$

$$\left(1 - \frac{c'}{\sqrt{n}}\right) \inf_{h} \mathcal{R}_{n}^{class}(\theta, h) - J^{2} e^{-n\beta} \leq \inf_{g} \mathcal{R}_{n}^{clust}(\theta, g) \leq \inf_{h} \mathcal{R}_{n}^{class}(\theta, h)$$

Analyzing the Bayes risk of clustering

Theorem

Assume $\delta = \min_{i,j} Q_{i,j} > 0$. Then,

- When J = 2

$$\delta(1-\alpha_n)\int f_0\wedge f_1\leq \inf_{g}\mathcal{R}_n^{clust}(\theta,g)\leq (1-\delta)\int f_0\wedge f_1$$

- When J > 2

$$\delta(1-\alpha_n)\Lambda - J^2 e^{-n\beta} \leq \inf_g \mathcal{R}_n^{clust}(\theta,g) \leq (1-\delta)\Lambda$$

where α_n decays to 0 and β depends on δ and J and

$$\Lambda = \int \min_{1 \le x_0 \le J} \sum_{x \ne x_0} f_x(y) dy$$

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Examples where HMMs are useful

- Data are generated through the same transition matrix $Q = \begin{pmatrix} 0.8 & 0.2 \\ 0.3 & 0.7 \end{pmatrix}$.
 - First example: A sample of size $n = 5.10^4$ is generated from two gaussian mixtures $:\frac{1}{2} (\mathcal{N}(1.7, 0.2) + \mathcal{N}(7, 0.15))$ and $\frac{1}{2} (\mathcal{N}(3.5, 0.2) + \mathcal{N}(5, 0.4)).$
 - Second example: A sample of size $n = 10^5$ is generated from two gaussian mixtures $:\frac{1}{2}(\mathcal{N}(3,0.6) + \mathcal{N}(7,0.4))$ and $\frac{1}{2}(\mathcal{N}(5,0.3) + \mathcal{N}(9,0.4)).$

Purpose: Retrieve the sequence of hidden states using only the observations.

Example 1

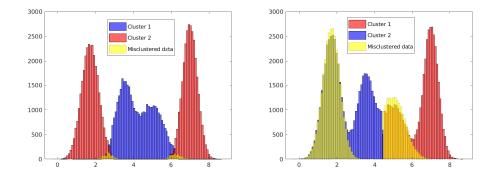


Figure: Histograms of the clusters. Left: clustering using plug-in classifier. Right: K-means clustering

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Example 2

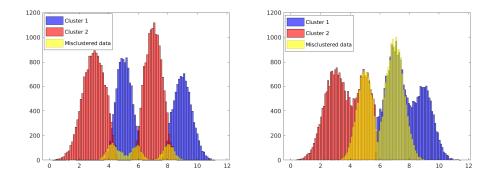


Figure: Histograms of the clusters. Left: clustering using plug-in classifier. Right: K-means clustering

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Clustering errors

	Bayes classifier	Plug-in classifier	K-means algorithm
Example 1	1.56%	1.61%	46.7%
Example 2	6.42%	6.51%	47.3%

Table: Errors of clustering using 3 algorithms: the Bayes classifier (using the true model parameters), the plug-in classifier (using the estimated parameters) and the K-means algorithm.

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